



Feedback Control of Dynamic Bipedal Robot Locomotion (Automation and Control Engineering)

Eric R. Westervelt, Jessy W. Grizzle, Christine Chevallereau, Jun Ho Choi, Benjamin Morris

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Feedback Control of Dynamic Bipedal Robot Locomotion (Automation and Control Engineering)

Eric R. Westervelt, Jessy W. Grizzle, Christine Chevallereau, Jun Ho Choi, Benjamin Morris Experimental implementations on two bipedal test beds

The elegance of the authors' approach is evident in the marriage of control theory and mechanics, uniting control-based presentation and mathematical custom with a mechanics-based approach to the problem and computational rendering. Concrete examples and numerous illustrations complement and clarify the mathematical discussion. A supporting Web site offers links to videos of several experiments along with MATLAB® code for several of the models. This one-of-a-kind book builds a solid understanding of the theoretical and practical aspects of truly dynamic locomotion in planar bipedal robots.

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Sylvia Ferland: What is your hobby? Have you heard in which question when you got scholars? We believe that that concern was given by teacher for their students. Many kinds of hobby, Every person has different hobby. And you also know that little person just like reading or as looking at become their hobby. You need to know that reading is very important along with book as to be the thing. Book is important thing to incorporate you knowledge, except your own teacher or lecturer. You get good news or update regarding something by book. Many kinds of books that can you choose to use be your object. One of them is niagra Feedback Control of Dynamic Bipedal Robot Locomotion (Automation and Control Engineering). Download and Read Online Feedback Control of Dynamic Bipedal Robot Locomotion (Automation and Control Engineering) Eric R. Westervelt, Jessy W. Grizzle, Christine Chevallereau, Jun Ho Choi, Benjamin Morris #YB8GO954J7X

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